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CHAPTER 3. VECTOR ANALYSIS 3.1.3

Position and Distance Vectors z_2 y_2

z_1 y_1 x_1 x_2 x y R_1 2 R_{12} z $P_1 = (x_1,$

$y_1, z_1)$ $P_2 = (x_2, y_2, z_2)$ O Figure 3-4

Distance vector $R_{12} = P_1P_2 = R_2 - R_1,$

where R_1 and R_2 are the position vectors of points P_1

and P_2 , respectively. Figure 3.3: The

notion of the position vector to a point, P

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Nawazish Ali Shah

$\hat{v} =$ unit vector along dr Chapter IV:
Vector Analysis In this chapter we shall be working primarily in the Cartesian system. Unless stated otherwise assume the system is Cartesian and any transformation, A , to another system is a rotation. Recall: in Cartesian systems, $g = 1$; $F_i = g_{ij} F_j$

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