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16.5a Relative Velocity

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POINTS OF Rotation in

mathematics is a concept

originating in geometry. Any

rotation is a motion of a certain

space that preserves at least one

point. It can describe, for

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example, the motion of a rigid body around a fixed point. A rotation is different from other types of motions: translations, which have no

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JOHN FRANKS Abstract. We
consider the (homological)
rotation vectors for area preserv-
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surfaces which are homotopic to the identity. There are two main results. The first is that if 0 is in the interior of ...

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POINTS OF AREA PRESERVING
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JOHN FRANKS Abstract. We consider the (homological) rotation vectors for area preserving diffeomorphisms of compact surfaces which are homotopic to the identity. There are two main

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results. The first is that if 0 is in the interior of the convex

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The coordinates of a point P may

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Points Of change due to either a rotation of the coordinate system CS , or a rotation of the point P . In the latter case, the rotation of P also produces a rotation of the vector v representing P . In other words, either P Page 4/29.

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We consider the (homological)
rotation vectors for area
preserving diffeomorphisms of
compact surfaces which are
homotopic to the identity. There
are two main results. The first is

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that if 0 is in the interior of the convex hull of the rotation vectors for such a diffeomorphism then f has a fixed point of positive index.

Rotation vectors and fixed points of area preserving ...

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the coordinate system CS , or a rotation of the point P . In the latter case, the rotation of P also produces a rotation of the vector v representing P . In other words, either P and v are fixed while CS rotates (alias), or CS is fixed while P and v rotate (alibi). Any given ...

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Rotation in mathematics is a concept originating in geometry. Any rotation is a motion of a certain space that preserves at least one point. It can describe, for example, the motion of a rigid body around a fixed point. A rotation is different from other

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types of motions: translations, which have no fixed points, and reflections, each of them having an entire n -dimensional flat of fixed points in a n -dimensional space. A clockwise rotation is a negative magnitude so a counterclockwise turn has a

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Rotation (mathematics) -
Wikipedia

the rotation Ω will rotate the
vector ω , changing its direction.
The magnitude of ω' is $\Omega\omega$, the
direction is normal to ω ; by
Coriolis theorem, the result is ω'

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$\mathbf{v} = \boldsymbol{\Omega} \times \mathbf{r}$. It is interesting to note that this result is independent of the distance b between the wheel and the axis of rotation for $\boldsymbol{\Omega}$. This is a consequence of our

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of area preserving surface
diffeomorphisms (1996) by J
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Sorted by: Results 1 - 10 of 21.
Next 10 → Distortion Elements in
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