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Cable driven robots (called as cable-suspended robots and wire-driven robots as well) are a type of parallel manipulators in which flexible cables are used as actuators. One end of each cable is reeled around a rotor twisted by a motor, and the other end is connected to the end-effector.

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*Cable robots - Wikipedia*

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Cable-driven parallel robots (CDPRs) are categorized as a type of parallel manipulators. In CDPRs, flexible cables are used to take the place of rigid links. The

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particular property of cables provides CDPRs several advantages, including larger workspaces, higher payload-to-weight ratio and lower manufacturing costs rather than rigid-link robots.

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This publication presents the outcome of the "First International Conference on Cable-Driven Parallel Robots" in 2012. This is the first conference to bring together the cable robot community and dedicate a forum for the international experts of this field.

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Cable-driven parallel robots (CDPRs) hold numerous advantages over conventional parallel robots in terms of high speed and large workspace. Cable-driven parallel robots



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whose workspace can be further increased by the modification of their geometric architecture are known as reconfigurable cable-driven parallel robots.

### *Wrench-Feasible Workspace of Mobile Cable-Driven Parallel ...*

This volume presents the outcome of the second forum to cable-driven parallel robots, bringing the cable robot community together. It shows the new ideas of the active researchers developing cable-driven robots. The book presents the state of the art, including both summarizing contributions as

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To tackle this challenge, this work proposes a method for increasing the number of cables without increasing actuators in a continuum robot through parallel platforms. The parallel platforms are used to control all the cables in the continuum robot, and can be separated from the continuum robot to enable the remote drive of a manipulation arm by using the cable-tube structure.

*Development of a Multi-Cable-Driven Continuum*

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*Robot ...*

concept of cable-driven parallel mechanisms – also referred to as wire-driven parallel mechanisms or tendon-driven parallel mechanisms – introduced in [7,8]. Cables are flexible members that can support very large tensile loads per unit weight. Compared to struts, they represent an even more effective use of materials which explains why they have been employed in construction and in machines since antiquity [9]. Cable-driven parallel mechanisms combine the principles of parallel ...

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*Cable-driven parallel mechanisms: state of the art and ...*

Cable driven parallel robots (CDPRs) are mechanisms which utilize cables instead of rigid links to actuate an end-effector.

*Dynamic trajectory planning of a 3-DOF under-constrained ...*

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*Spiral: Cable-driven parallel mechanisms for minimally ...*

This publication presents the outcome of the "First International Conference on Cable-Driven Parallel Robots" in 2012. This is the first conference to bring together the cable robot community and dedicate a forum for the international experts of this field. It contains the Know-how, ideas and

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Cable-driven parallel mechanism (CDPM) is a kind of flexible parallel mechanisms. Unlike its counterpart, the rigid-body parallel mechanism, a CDPM controls the pose of mobile platform by adjusting the length of cables,

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with which the mobile platform is suspended in the space.

*Kinematic analysis of cable-driven parallel mechanisms ...*

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2 Description of Cable-Driven Parallel-Series



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(CDPS) Hybrid Mechanism The proposed mechanism includes a lower plate and an upper plate which are used to hold the compression spring in con- centric position as shown in Fig.1. The structure is driven by three cables pulled or set free by three servo motors located underneath the CDPS mechanism.

### *Design and Modelling of a Cable-Driven Parallel-Series ...*

Reichert C, Müller K, Bruckmann T (2014) Internal force-based impedance control for cable-driven parallel robots. In: New trends in mechanism and machine science, mechanisms

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